

3. Linear Least Squares

- Example
- QR factorization

Positive semi-definite matrix.

Definition:

A symmetric matrix $A \in \mathbb{R}^{n \times n}$ is positive semi-definite if $x^T A x \geq 0$ for all $x \in \mathbb{R}^n$.

Notation: $A \succeq 0$

Similarly, A symmetric matrix $A \in \mathbb{R}^{n \times n}$ is positive definite if $x^T A x > 0$ for all non-zero $x \in \mathbb{R}^n$ ($A \succ 0$)

If x is an eigenvector of A , $Ax = \lambda x$
 $\Rightarrow x^T A x = \lambda \underbrace{x^T x}_{\geq 0} \geq 0$
 $\Rightarrow \lambda \geq 0$

Q. Which of the following statements are true.

- i. If A is PSD, A is invertible.
- ii. If A is PD, A^{-1} exists and A^{-1} is also PD.
- iii. Let $f(x) = \|Ax - b\|_2^2$. For all x , the Hessian of f has non-negative eigenvalues.

pick one:

A) i

B) i, ii

C) ii, iii

Least squares

$$\underset{x}{\text{minimize}} \quad f(x) := \frac{1}{2} \|Ax - b\|_2^2 = \frac{1}{2} \sum_{i=1}^m (a_i^T x - b_i)^2$$

$$f(x) = \frac{1}{2} \langle Ax - b, Ax - b \rangle = \frac{1}{2} \langle Ax, Ax \rangle - \langle Ax, b \rangle + \langle b, b \rangle$$

$$= \frac{1}{2} \langle A^T A x, x \rangle - \langle A^T b, x \rangle + \|b\|^2$$

$$\nabla f(x) = A^T (Ax - b)$$

- Gradient

- Hessian

$$\nabla^2 f(x) = A^T A$$

$$x^T A^T A x = \|Ax\|_2^2 \geq 0$$

- Is the Hessian positive definite? positive semidefinite?

column

Ans: Always positive semidefinite. Positive definite if A has full rank.

- Conditions for $x = x^*$ to be a global minimizer?

$$A^T (Ax^* - b) = 0$$

These are the **normal equations** of the least squares problem.

QR factorization

Orthogonal and orthonormal vectors

Two vectors $x \in \mathbf{R}^n$, $y \in \mathbf{R}^n$

- Recall cosine identity

$$x^T y = \|x\|_2 \|y\|_2 \cos(\theta)$$

- x and y are orthogonal if they are “perpendicular”

$$x^T y = 0 \quad (\cos(\theta) = 0)$$

- x and y are orthonormal if they are orthogonal and normalized

$$x^T y = 0, \quad x^T x = 1, \quad y^T y = 1$$

Orthogonal matrix

$Q \in \mathbf{R}^{n \times n}$ is orthogonal if its columns are all pairwise orthonormal

$$Q = [q_1 \quad \cdots \quad q_n], \quad Q^T Q = Q Q^T = I$$

- Then the inverse is the transpose

$$Q^{-1} = Q^T$$

- Inner products are “invariant” under orthogonal transformations

$$(Qx)^T(Qy) = x^T Q^T Q y = x^T y$$

- 2-norm is also invariant

$$\|Qx\|_2 = \|x\|_2$$

- Determinant is either 1 or -1. (Why?)

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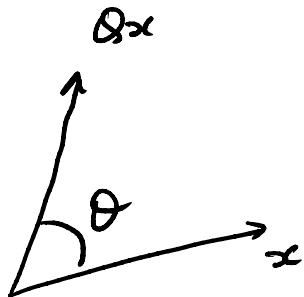
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$$\det(I) = \det(Q^T Q) = \det(Q)^2 = 1$$

Example

The rotation matrix

$$Q = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$



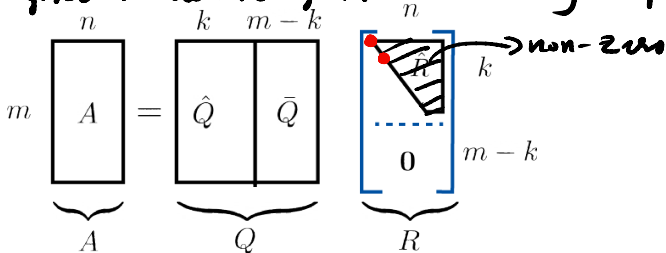
is orthogonal.

Check:

$$Q^T Q = \begin{pmatrix} \cos^2 \theta + \sin^2 \theta & 0 \\ 0 & \cos^2 \theta + \sin^2 \theta \end{pmatrix}$$
$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

QR Factorization

Assume the first k columns of A are linearly indep.



where

- Q is orthogonal ($Q^T Q = Q Q^T = I$)
- R is upper triangular ($R_{ij} = 0$ whenever $i > j$)
- \hat{Q} spans the range of A
- \bar{Q} spans the nullspace of A^T ,

$$R(A) \oplus N(A^T) = \mathbb{R}^m$$

In Julia,

$$(Q, R) = \text{qr}(A)$$

Always exists for any $A \in \mathbb{R}^{m \times n}$

Reduced ("thin", "economode") QR factorization

For $A \in \mathbf{R}^{m \times n}$ full rank

$$\begin{array}{c} m \\ \boxed{A} \end{array} = \begin{array}{c} n \\ \boxed{\hat{Q}} \end{array} \begin{array}{c} n \\ \hat{R} \end{array}$$

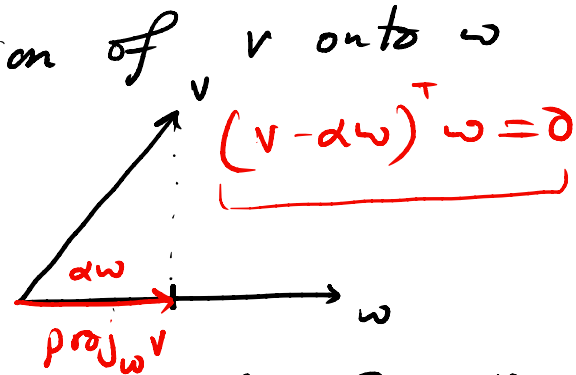
Equivalently,

$$\begin{aligned} a_1 &= r_{11} q_1 \\ a_2 &= r_{12} q_1 + r_{22} q_2 \\ a_3 &= r_{13} q_1 + r_{23} q_2 + r_{33} q_3 \\ &\vdots \\ a_n &= r_{1n} q_1 + r_{2n} q_2 + \cdots + r_{nn} q_n \end{aligned}$$

Using Projection to find Q .

Given vectors $v, w \in \mathbb{R}^n$, the projection of v onto w

$$\text{is } \text{proj}_w v = \frac{w^T v}{w^T w} w$$



Given a matrix $A = [a_1 \ a_2 \ \dots \ a_n]$

we can find Q with $\mathcal{R}(Q) = \mathcal{R}(A)$ and Q orthogonal by:

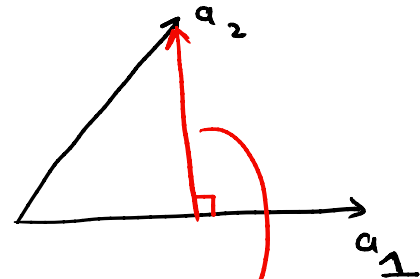
$$\tilde{q}_1 = a_1$$

$$\tilde{q}_2 = a_2 - \text{proj}_{\tilde{q}_1} a_2$$

\vdots

$$\tilde{q}_n = a_n - \text{proj}_{\tilde{q}_1} a_n - \dots - \text{proj}_{\tilde{q}_{n-1}} a_n$$

$$q_k = \tilde{q}_k / \|\tilde{q}_k\|_2$$



$$q_2 = a_2 - \text{proj}_{a_1} a_2$$

Solving least squares via QR

$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \quad \frac{1}{2} \|Ax - b\|_2^2$$

$$x = \begin{bmatrix} a \\ b \end{bmatrix}$$

Because 2-norm is invariant under orthogonal transformation,

$$\begin{aligned} \|Ax - b\|_2^2 &= (Ax - b)^T (Ax - b) \\ &= (Ax - b)^T Q^T Q (Ax - b) \\ (Q(Ax - b))^T (-) &= \|Q^T (Ax - b)\|_2^2 \\ &= \left\| \begin{bmatrix} \hat{R} \\ 0 \end{bmatrix} x - \begin{bmatrix} \hat{Q}^T \\ \bar{Q}^T \end{bmatrix} b \right\|_2^2 \\ &= \underbrace{\|\hat{R}x - \hat{Q}^T b\|_2^2}_{(1)} + \underbrace{\|\bar{Q}^T b\|_2^2}_{(2)} \end{aligned}$$

$$\begin{aligned} \|x\|_2^2 &= \|a\|_2^2 + \|b\|_2^2 \end{aligned}$$

$$Q^T = \begin{bmatrix} \hat{Q}^T \\ \bar{Q}^T \end{bmatrix}$$

(1) is minimized when $\hat{R}x = \hat{Q}^T b$, (2) is constant

Geometric perspective

$$P = \begin{bmatrix} 0 & 0 \\ \alpha & 1 \end{bmatrix}$$

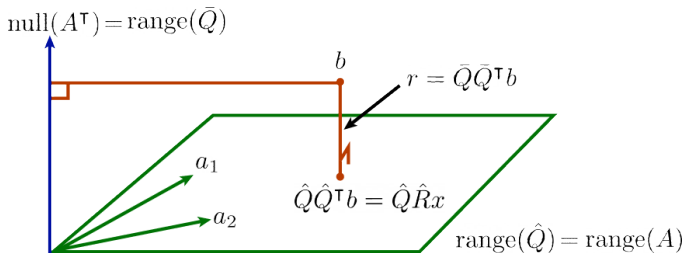
- Orthogonal projection matrix:

1. A square matrix P is a projection matrix if $P^2 = P$.
2. A projection matrix P is an orthogonal projection matrix if $P = P^T$.

- Let $A = QR$.

$$P^2 = P$$

1. $\hat{Q}\hat{Q}^T$ and $\bar{Q}\bar{Q}^T$ are orthogonal projection matrices.
2. For any $b \in \mathbf{R}^m$, $\hat{Q}\hat{Q}^T b$ is the closet point in **range**(A) w.r.t. 2-norm.
3. For any $b \in \mathbf{R}^m$, $\bar{Q}\bar{Q}^T b$ is the closet point in **null**(A^T) w.r.t. 2-norm.



Solving least squares via QR

$$\underset{x \in \mathbf{R}^n}{\text{minimize}} \quad \frac{1}{2} \|Ax - b\|_2^2$$

Mathematically

$$\begin{aligned} A^T A x &= A^T b \\ R^T Q^T Q R x &= R^T Q^T b \\ R x &= Q^T b \\ x &= R^{-1} Q^T b \end{aligned}$$

Computationally

1. Compute $A = \hat{Q}\hat{R}$
2. Compute $y = \hat{Q}^T b$
3. Solve $\hat{R}x = y$

More computationally stable than solving $A^T A x = A^T b$ by forming $A^T A$