

Constrained optimization

$$\min_{x \in \mathbb{R}^n} f(x) \quad \text{s.t.} \quad x \in S \quad \text{--- (1)}$$

- $f: \mathbb{R}^n \rightarrow \mathbb{R}$ is differentiable
- S is convex set
- If $S = \mathbb{R}^n$: x^* is stationary $\Leftrightarrow \nabla f(x^*) = 0$.

Defⁿ: (Stationary point) x^* is called a stationary point of (1) if $\nabla f(x^*)^T (x - x^*) \geq 0$ for any $x \in C$.

There is no feasible descent direction of f at x^* .

Stationary point in \mathbb{R}^n .

If $C = \mathbb{R}^n$, the stationary points are x^* satisfying

$$\nabla f(x^*)^T (x - x^*) \geq 0$$

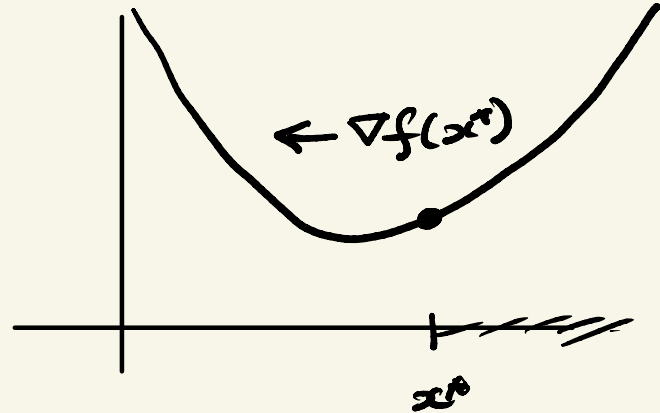
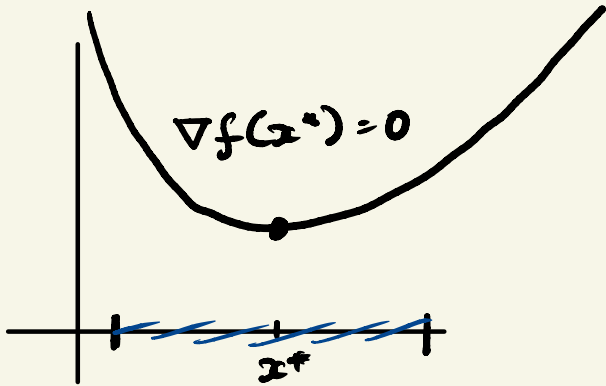
for all $x \in \mathbb{R}^n$.

pick $x = x^* - \nabla f(x^*) \Rightarrow -\|\nabla f(x^*)\| \geq 0$
 $\Rightarrow \nabla f(x^*) = 0.$

Reduces to stationary condition for $S = \mathbb{R}^n$.

Necessary Condition

Thm: Let f be a continuously differentiable function over a convex set S and let x^* be a local minimum of (1). Then x^* is a stationary point:



Example

$$\min_{x \in \mathbb{R}^n} f(x) \quad \text{s.t.} \quad x_i \geq 0 \quad i=1, \dots, n$$

Characterize the stationary points: Assume x^* is stationary.

$$\Leftrightarrow \nabla f(x^*)^T (x - x^*) \geq 0 \quad \forall x_i \geq 0$$

$$\Leftrightarrow \nabla f(x^*)^T x - \nabla f(x^*)^T x^* \geq 0 \quad \forall x_i \geq 0$$

$$\Leftrightarrow \nabla f(x^*) \geq 0 \quad \text{and} \quad -\nabla f(x^*)^T x^* \geq 0$$

(Why? because $a^T x + b \geq 0$ for all $x \geq 0 \Leftrightarrow a \geq 0, b \geq 0$)

Note that $x^* \geq 0$ and $\nabla f(x^*) \geq 0 \Rightarrow x_i^* \frac{\partial f}{\partial x_i}(x^*) =$

So,

$$\frac{\partial f}{\partial x_i}(x^*) \begin{cases} = 0, & x_i^* \geq 0 \\ \geq 0, & x_i^* = 0 \end{cases}$$

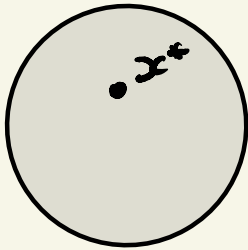
Normal core.

We can express necessary condition in terms of normal core.

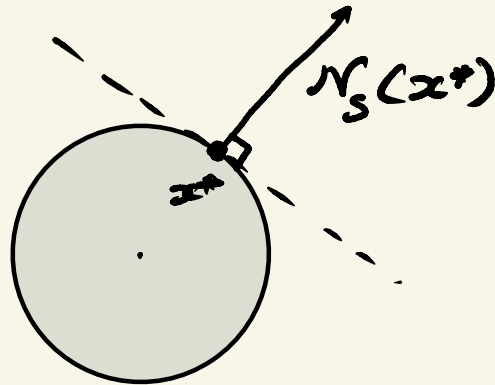
For $x \in S$, define the normal core of S at x

$$\mathcal{N}_S(x) = \{g \in \mathbb{R}^n : g^T(z-x) \leq 0, \forall z \in S\}$$

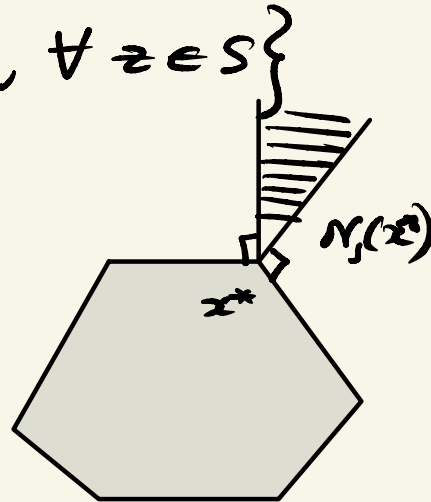
$$\mathcal{N}_S(x^*) = \{0\}$$



interior



smooth boundary



non-smooth bnd.

Example

1. Let $S = \{z\}$.

$$N_S(x) = \begin{cases} \mathbb{R}^n & \text{if } x = z \\ \emptyset & \text{otherwise.} \end{cases}$$

2. Let $S = \{x \mid \|x\|_2 \leq 1\}$

$$N_S(x) = \begin{cases} x & \text{if } \|x\|_2 = 1 \\ \{0\} & \text{if } \|x\|_2 < 1 \\ \emptyset & \text{otherwise.} \end{cases}$$

Stationary point and normal cone

Thm: Let f be a continuously differentiable function over a convex set S and let x^* be a local minimum of (1). Then

$$-\nabla f(x^*) \in N_S(x^*).$$

Example: x is in interior of S .

We say that $x \in \mathbb{R}^n$ is in the interior of S

($x \in \text{int}(S)$) if

there exists $\varepsilon > 0$ such that for all $v \in \mathbb{R}^n$, $x + \varepsilon v \in S$.

Let $S = \{x \mid \|x\|_2 = 1\}$, $\text{int}(S) = \emptyset$.

Let $S = \{x \mid \|x\|_2 \leq 1\}$, $\text{int}(S) = \{x \mid \|x\|_2 < 1\}$.

Claim For any $x \in \text{int}(S)$, S convex,

$$N_S(x) = \{0\}.$$

proof: For any g , pick $v = g$ or $v = -g$.
 $\varepsilon g^T v = g^T(z - x) > 0$, $z = x + \varepsilon v \in S$.
or $-\varepsilon g^T v = g^T(z - x) > 0$, $z = x - \varepsilon v \in S$.

Example: Normal cone to affine set

$$N_S(x) = \{g \in \mathbb{R}^n \mid g^T(z-x) \leq 0, \forall z \in S\}$$

Affine set $S = \{x \mid Ax = b\}$. $\nearrow \in N(A)$

• Trick: shift the set. Define $S' = \{z-x \mid z \in S\}$.

$$\begin{aligned} \text{Then } N_S(x) &= \{g \in \mathbb{R}^n \mid g^T u \leq 0, \forall u \in S'\} \\ &= \{g \in \mathbb{R}^n \mid g^T u \leq 0, \forall u \in N(A)\} \end{aligned}$$

• If $u \in N(A)$ and $g^T u \leq 0$, then $-u \in N(A)$ and $-g^T u \geq 0$.

• Therefore, $N_S(x) = \{g \in \mathbb{R}^n \mid g^T u = 0, \forall u \in N(A)\} = R(A^T)$

• Verify: pick any $g \in R(A^T)$. Then

$$g^T(z-x) = v^T A(z-x) = v^T(b-b) = 0.$$

Example: Normal cone to affine halfspace.

Affine halfspace: $S = \{x \mid Ax \leq b\} = \{x : a_i^T x \leq b_i, i=1, \dots, m\}$

What is the normal cone of S ?

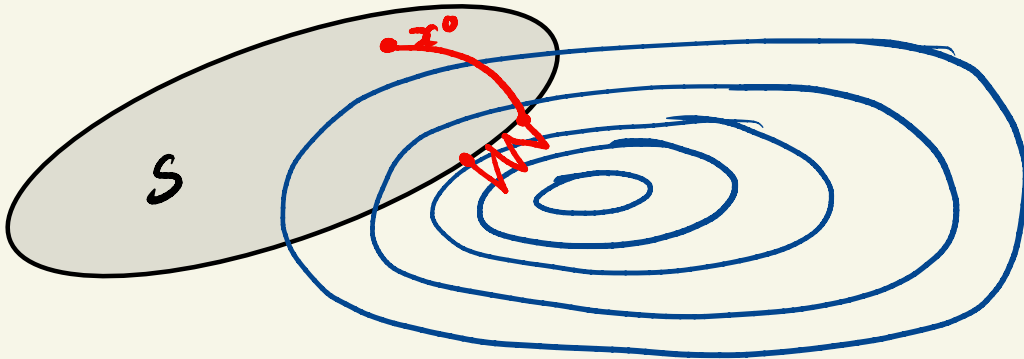
Projected gradient descent.

$$\min_x f(x) \quad \text{s.t. } x \in S$$

projected gradient descent:

$$x^{k+1} = \text{proj}_S(x^{(k)} - \alpha^{(k)} \nabla f(x^{(k)})),$$

where $\text{proj}_S(z) = \arg \min_{x \in S} \|x - z\|_2$.



Geometry of projection.

$$\text{proj}_S(z) = \arg \min_{x \in S} \frac{1}{2} \|x - z\|_2^2$$

- If $x \in S$ then $\text{proj}_S(x) = x$.
- optimality cond. for projection: since $\nabla p(x) = x - z$
 $x = \text{proj}_S(z) \Leftrightarrow (z - x)^T (y - x) \leq 0 \quad \forall y \in S.$

